

Alternation Is Strict For Higher-Order Modal Fixpoint Logic

Alternating Krivine Automata and Alternation

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Motivation

HFL: Higher-order Modal Fixpoint Logic: \mathcal{L}_μ + simply typed lambda calculus

Alternating Parity Krivine Automata (APKA): Operational semantics for HFL

Motivation:

- enables local model-checking techniques
- automaton-based characterization of alternation
- possible intermediate to higher-order recursion schemes

Types

simple types given via $\tau ::= \text{Pr} \mid \tau \rightarrow \tau$

because of right-associativity: $\tau = \tau_1 \rightarrow \dots \rightarrow \tau_m \rightarrow \text{Pr}$

each type induces a complete lattice over transition system $\mathcal{T} = (\mathcal{S}, \rightarrow, L)$ using pointwise orderings \sqsubseteq

$$\begin{aligned} \llbracket \text{Pr} \rrbracket &:= (2^{\mathcal{S}}, \sqsubseteq) \\ \llbracket \sigma \rightarrow \tau \rrbracket &:= (\llbracket \sigma \rrbracket \rightarrow_{\text{mon.}} \llbracket \tau \rrbracket, \sqsubseteq) \end{aligned}$$

Syntax of HFL

HFL = modal μ -calculus + simply typed λ -calculus

[Viswanathan² '04]

$$\varphi ::= q \mid \neg q \mid X \mid \varphi \vee \varphi \mid \langle a \rangle \varphi \mid \mu(X : \tau). \varphi \mid \lambda(X : \tau). \varphi \mid \varphi \varphi$$

plus duals $\varphi \wedge \psi$, $[a]\varphi$, $\nu(X : \tau)$ *natively*

well-formedness condition given by **type system** (not given here)

NB: can allow negation on arbitrary formulae, cope with extended type system

An Example Formula

Consider $(\mu X. \lambda x. x \vee (X [a]x)) P$.

Unfolding via $\sigma X. \psi = \psi[\sigma X. \psi / X]$ yields
 $(\lambda x. x \vee (\mu X. \lambda x'. x' \vee (X [a]x'))) [a]x) P$.

Using β -reduction we get
 $P \vee (\mu X. \lambda x'. x' \vee (X [a]x')) [a]P$.

More unfolding:
 $P \vee (\lambda x'. x' \vee (\mu X. \lambda x''. x'' \vee (X [a]x''))) [a]x') [a]P$.

More β -reduction:
 $P \vee [a]P \vee (\mu X. \lambda x''. x'' \vee (X [a]x''))) [a][a]P$.

We get: $P \vee [a]P \vee [a][a]P \vee \dots = \bigvee_{i=0}^n [a]^i P$

uniform inevitability!

Operational Semantics for HFL

proposed automaton model: **Alternating Parity Krivine Automata (APKA)**

- **alternation** for Boolean and modal operators ($\vee, \wedge, \langle a \rangle, [b]$)
- (stair-) **parity** condition for fixpoints
- **Krivine Abstract Machine** for higher-order features

challenge: get acceptance condition right, i.e., synchronize parity condition with Krivine machine

Alternating Parity Krivine Automata

APKA of index m is $\mathcal{A} = (\mathcal{X}, \delta, I, \Lambda, (\tau_X)_{X \in \mathcal{X}})$ where

- finite set of (fixpoint) **states** $\mathcal{X} = \{X_1, \dots, X_n\}$
- **priority** function $\Lambda: \mathcal{X} \rightarrow [1, m]$, resp. $[0, m - 1]$
- **transition** function $\delta: X \mapsto \varphi_X$, generated from

$$\psi ::= P \mid \neg P \mid \psi \wedge \psi \mid \psi \vee \psi \mid \langle a \rangle \psi \mid [a] \psi \mid f_i^X \mid X' \mid (\psi \psi)$$

where f_i^X of type τ_i^X for $i \leq n_X$ and φ_X of type τ_X .

- assignment of argument and value types

$$\tau_X = \tau_1^X \rightarrow \dots \rightarrow \tau_{n_X}^X \rightarrow \text{Pr}$$

- $I \in \mathcal{X}$ initial state with $\tau_I = \text{Pr}$

state space is $\mathcal{Q} = \mathcal{X} \cup \bigcup_{X \in \mathcal{X}} \text{sub}(\delta(X))$

Environments and Closures

environments handle variable lookup

$$e ::= e_0 \mid e = (f_1^X \mapsto (\psi_1, e_1), \dots, f_{n_X}^X \mapsto (\psi_{n_X}, e_{n_X}), e')$$

e' is **parent environment**

(ψ, e_i) called **closure**

variable **lookup**:

$$e(f) = \begin{cases} (\psi_i, e_i) & , \text{ if } f = f_i^X \\ \text{undefined} & , \text{ otherwise} \end{cases}$$

Configurations

APKA accept LTS; explained in terms of 2-player game on configurations of the form

$$C = (s, (\psi, e), e', \Gamma, \Delta)$$

where

- s is current **state** in LTS
- (ψ, e) current **closure** with $\psi \in \mathcal{Q}$, e environment
- e' distinguished environment (point of **current** computation)
- $\Gamma = (\psi_n, e_n), \dots, (\psi_1, e_1)$ **stack** of closures
- Δ stack of **priorities**

only use well-formed configurations (all environments defined etc.)

Acceptance of APKA

run over \mathcal{T} , s_0 starts in $(s_0, (I, e_0), e_0, \epsilon, \epsilon)$

game played between **V** and **R**:

- players move as per the transition relation (below)
- automaton accepts structure if **V** wins
- player who gets stuck loses
- infinite plays \rightsquigarrow stair-parity condition on sequence of priority stacks

transition from $(s, (\psi, e), e', \Gamma, \Delta)$ depending on ψ

- $\psi = P$ or $\psi = \neg P$: **V** wins iff $\mathcal{T}, s \models \psi$
- $\psi = \psi_1 \vee \psi_2$: **V** chooses i , continue at $(s, (\psi_i, e), e', \Gamma, \Delta)$
- $\psi = [a]\psi'$: **R** chooses $s \xrightarrow{a} t$, cont. at $(t, (\psi', e), e', \Gamma, \Delta)$
- ...

More Game Moves

transition from $(s, (\psi, e), e', \Gamma, \Delta)$ depending on ψ

- $\psi = (\psi_1 \psi_2)$: continue at $(s, (\psi_1, e), e', \Gamma \cdot (\psi_2, e), \Delta)$
- $\psi = X$: continue $(s, (\delta(X), e''), e'', \epsilon, \Delta \cdot \Lambda(X))$ where $\Gamma = C_1, \dots, C_{n_X}$ and $e'' = (f_1^X \mapsto C_1, \dots, f_{n_X}^X \mapsto C_{n_X}, e')$ new
- $\psi = f$ not of ground type: go to $(s, e(f), e', \Gamma, \Delta)$
- $\psi = f$ of ground type : go to $(s, (\psi', e''), e'', \Gamma, \Delta')$ where $e(f) = (\psi', e'')$ and Δ' is Δ with as many priorities removed as are between e' and e''

special role for ground type variables: undo priorities until “caller” is reached

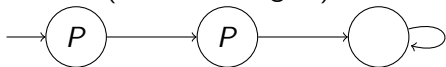
An Example

Consider $\mathcal{A} = (\mathcal{X}, \Lambda, l, \delta, (\tau_X)_{X \in \mathcal{X}})$ with

- $\mathcal{X} = \{I, X, Y\}$
- $\tau_I = \tau_Y = \text{Pr}, \tau_X = \text{Pr} \rightarrow \text{Pr}$
- $\Lambda(I) = \Lambda(X) = 1, \Lambda(Y) = 0$
- $\delta(I) = \emptyset \mapsto (X \neg P)$
- $\delta(X) = x: \text{Pr} \mapsto (\diamond x) \vee \square Y$
- $\delta(Y) = \emptyset \mapsto (X Y)$

Equivalent to $(\mu X. \lambda x. \diamond x \vee \square \nu Y. (X Y)) \neg P$

Run over (tree-unfolding of) this structure:



An Example Run

$$C_0 = (s_1, (I, e_0), e_0, \epsilon, \epsilon)$$

$$C_1 = (s_1, ((X \neg P), e_0), e_0, \epsilon, 1)$$

$$C_2 = (s_1, (X, e_0), e_0, (\neg P, e_0), 1)$$

$$C_3 = (s_1, (((\diamond x) \vee \square Y), e_1), e_1, \epsilon, 11)$$

$$C_4 = (s_1, ((\square Y), e_1), e_1, \epsilon, 11)$$

$$C_5 = (s_2, (Y, e_1), e_1, \epsilon, 11)$$

$$C_6 = (s_2, ((X Y), e_2), e_2, \epsilon, 110)$$

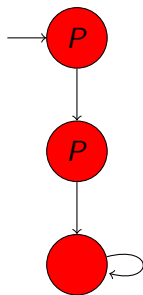
$$C_7 = (s_2, (X, e_2), e_2, (Y, e_2), 110)$$

$$C_8 = (s_2, (((\diamond x) \vee \square Y), e_3), e_3, \epsilon, 1101)$$

$$C_9 = (s_2, ((\diamond x), e_3), e_3, \epsilon, 1101)$$

$$C_{10} = (s_3, (x, e_3), e_3, \epsilon, 1101)$$

$$C_{11} = (s_3, (Y, e_2), e_2, \epsilon, 110)$$



$$e_1 = (x \mapsto (\neg P, e_0), e_0)$$

$$e_2 = (\epsilon, e_1)$$

$$e_3 = (x \mapsto (Y, e_2), e_2)$$

Fixpoint Alternation

higher-order does not conquer fixpoint alternation

Theorem 1

For every $m \geq 2$ there is an APKA \mathcal{A}_m index m that is not equivalent to any APKA of index $< m$.

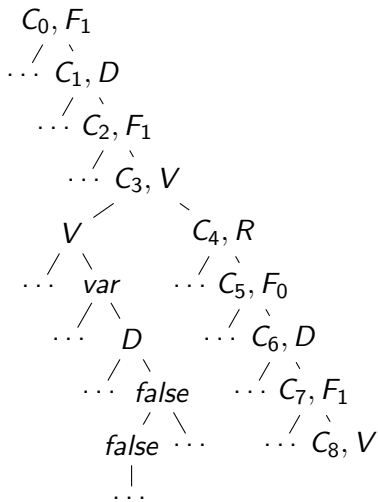
NB: \mathcal{A}_m independent of type order

also induces alternation hierarchy on HFL

Sketch of the proof

- F.a. m fix suitable vocabulary τ_m and restrict to fully binary infinite trees
- Take **game tree** for acceptance game of a run of order- m automaton as underlying set of new LTS
- **Annotate** (via propositions) nodes in tree (configurations in game) **depending** on who moves, parity stack operations \rightsquigarrow new tree \mathcal{T} .

Game Tree



$$C_0 = (s_1, (I, e_0), e_0, \epsilon, \epsilon)$$

$$C_1 = (s_1, ((X \neg P), e_0), e_0, \epsilon, 1)$$

$$C_2 = (s_1, (X, e_0), e_0, (\neg P, e_0), 1)$$

$$C_3 = (s_1, (((\diamond x) \vee \square Y), e_1), e_1, \epsilon, 11)$$

$$C_4 = (s_1, ((\square Y), e_1), e_1, \epsilon, 11)$$

$$C_5 = (s_2, (Y, e_1), e_1, \epsilon, 11)$$

$$C_6 = (s_2, ((X Y), e_2), e_2, \epsilon, 110)$$

$$C_7 = (s_2, (X, e_2), e_2, (Y, e_2), 110)$$

$$C_8 = (s_2, (((\diamond x) \vee \square Y), e_3), e_3, \epsilon, 1101)$$

Sketch of the proof

- F.a. m fix suitable vocabulary τ_m and restrict to fully binary infinite trees
- Take **game tree** of acceptance game of a run of order- m automaton as underlying set of new LTS
- **Annotate** (via propositions) nodes in tree (configurations in game) **depending** on who moves, parity stack operations \rightsquigarrow new tree \mathcal{T} .
- F.a. m there is fixed \mathcal{A}_m s.t. $\mathcal{T} \models \mathcal{A}_m$ iff \mathbf{V} wins underlying game
- This operation is **contraction** on metric space of f.b.i. trees \rightsquigarrow obtain **fixpoint** via Banach Fixpoint Theorem
- **No** automaton of index $< m$ can be equivalent to \mathcal{A}_m over this fixpoint